

Unit One: Vectors and Scalars; 1D Motion in equilibrium

Skills 1-11

Facts and Concepts

- Values expressed in correct scientific notation have a coefficient greater than 10⁻¹ but less than 10⁰.
- Scalar quantities DO NOT require direction for calculation. They have magnitude only. Distance, Speed, mass, time, Energy, work, Power, most electricity variables (except force & field lines)
- Vector quantities - DO require direction for calculation - Magnitude & Direction
- Displacement, velocity, acceleration, field strength, force

Parallel Vectors

Assign + or -

"x"	East	West
"y"	right	left
"z"	North	South
	up	down

Add including sign

Max resultant occurs for two parallel vectors in the same direction (0° difference), min resultant occurs for two parallel vectors in opposite directions (180° difference)

- Objects that are moving at constant speed are in equilibrium
Equilibrium means all forces are balanced (ie $\sum F_{net} = 0$)

with equal spacing

- Fast
- Large spacing
- More distance for equal time frames
- Slow

Variables, Equations and Units

A = resultant
 A_x = horizontal component
 A_y = vertical component
 θ = angle for x axis

$$A = \sqrt{A_x^2 + A_y^2}$$

$$\theta = \tan^{-1}\left(\frac{A_y}{A_x}\right)$$

$$\theta = \cos^{-1}\left(\frac{A_x}{A}\right)$$

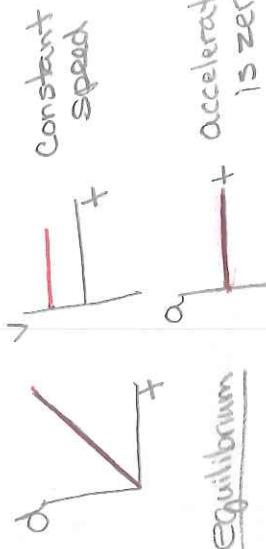
$$\theta = \sin^{-1}\left(\frac{A_y}{A}\right)$$

A can be substituted for any vector
 d (displacement), v (velocity)

$$\nabla = d/t$$

distance/displacement
 cm/s
 speed/velocity
 cm/s
 time
 (s)

Graphs and other skills



+ acceleration is zero

Small angle between 2 vectors leads to large+resultant & vice versa

Perpendicular Vectors

- Identify horizontal component (A_x), vertical component (A_y), the resultant (A), or direction (θ)



Angle or direction
 always relative to 1st
 axis drawn
 + theory

If more than 1 vector is present on an axis simplify to
 sum of horizontal & sum of vertical

Max resultant occurs for
 two parallel vectors in
 the same direction (0° difference),

Min resultant occurs for
 two parallel vectors in
 opposite directions (180° difference)

Constant speed

equilibrium

+ acceleration is zero